

MAS.S63: Design for DIY Manufacturing Electronics Prototyping

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diymanufacturing.mit.edu

Outline

- Assignment
- Prototyping
- Elements (sensing, actuation, power, etc.)
- Resources
- Advice
- Circuits

Assignment

The Larger Process

- Prototyping the electronics
- Prototyping the form
- Combining the two prototypes (mid-term)
- Designing for production (final)

Assignment

- Build a functioning (electronic) prototype of your project
- Includes essential mechanical aspects
- Not (really) worrying about production process

Goal

- Find out if what you're doing is possible
- Experience it
- Figure out how to implement it

This is a prototype.

- Arduino board is fine
- Custom PCBs after the mid-term
- Need to test all the elements

Schedule

- Need to order parts tomorrow
- Nan-Wei and I are available tomorrow
- Arduino section? Sensor section?
- Office hours next week, too.

Prototyping

What do prototypes prototype?

- role
- look & feel
- implementation

Bill Verplank

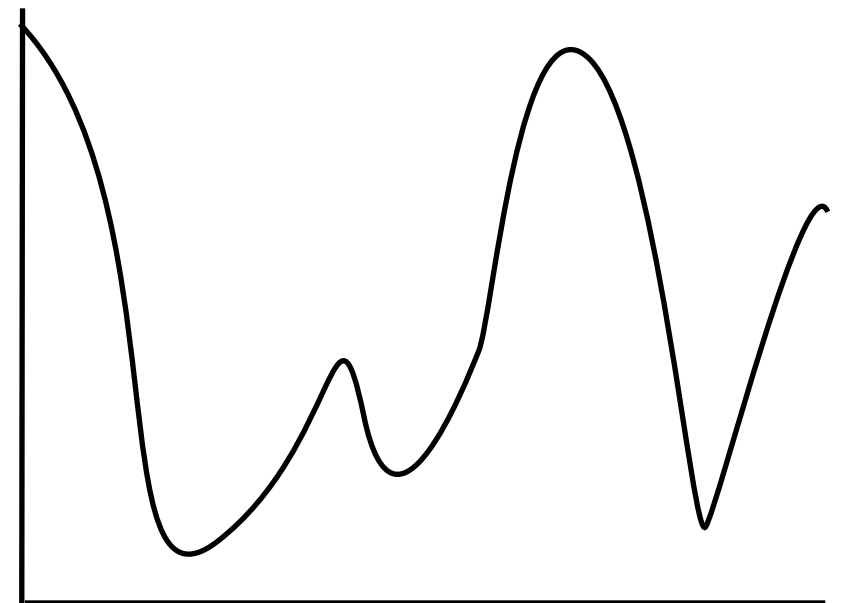
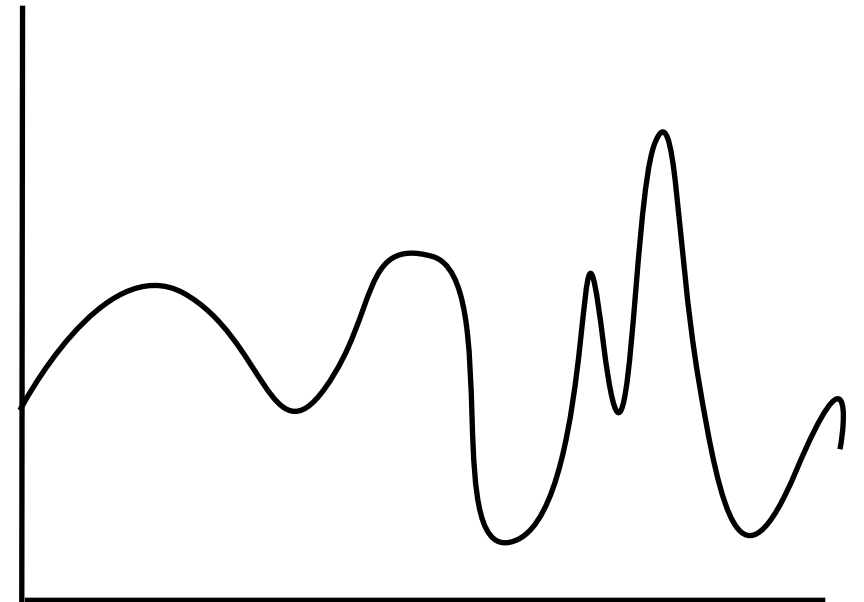
INTERACTION DESIGN



Questions

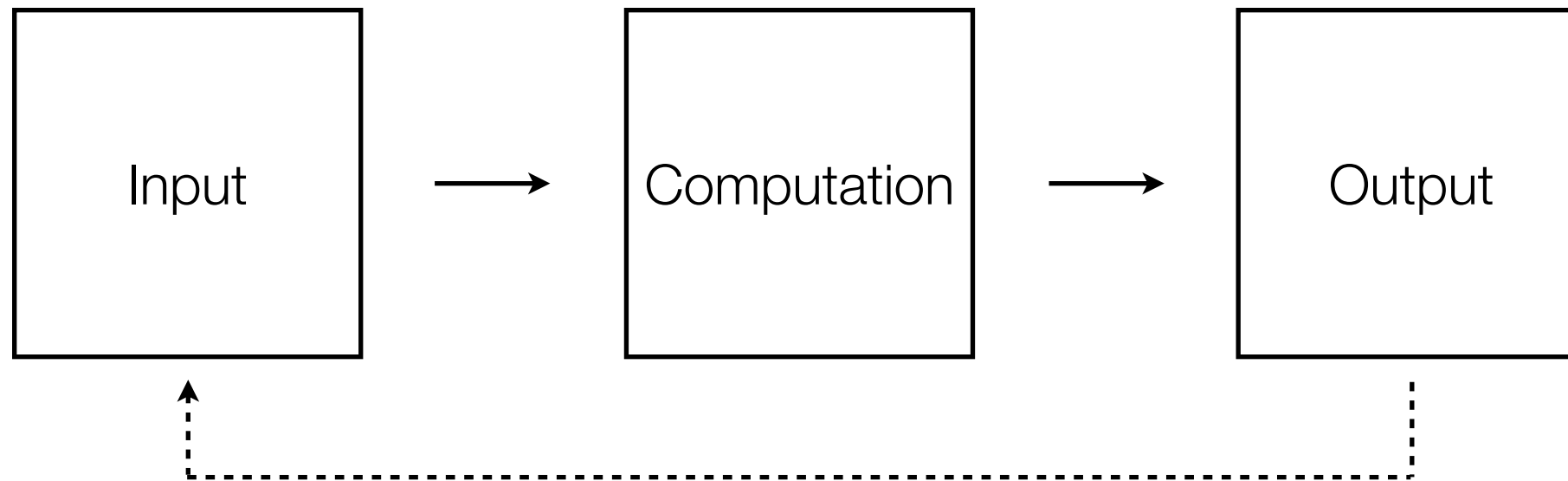
- What do you need to sense?
- What do you need to actuate?
- How are you going to power it?
- What do you need to communicate with?
- How are you going to put it together?

From Physical World to Electrical Signal

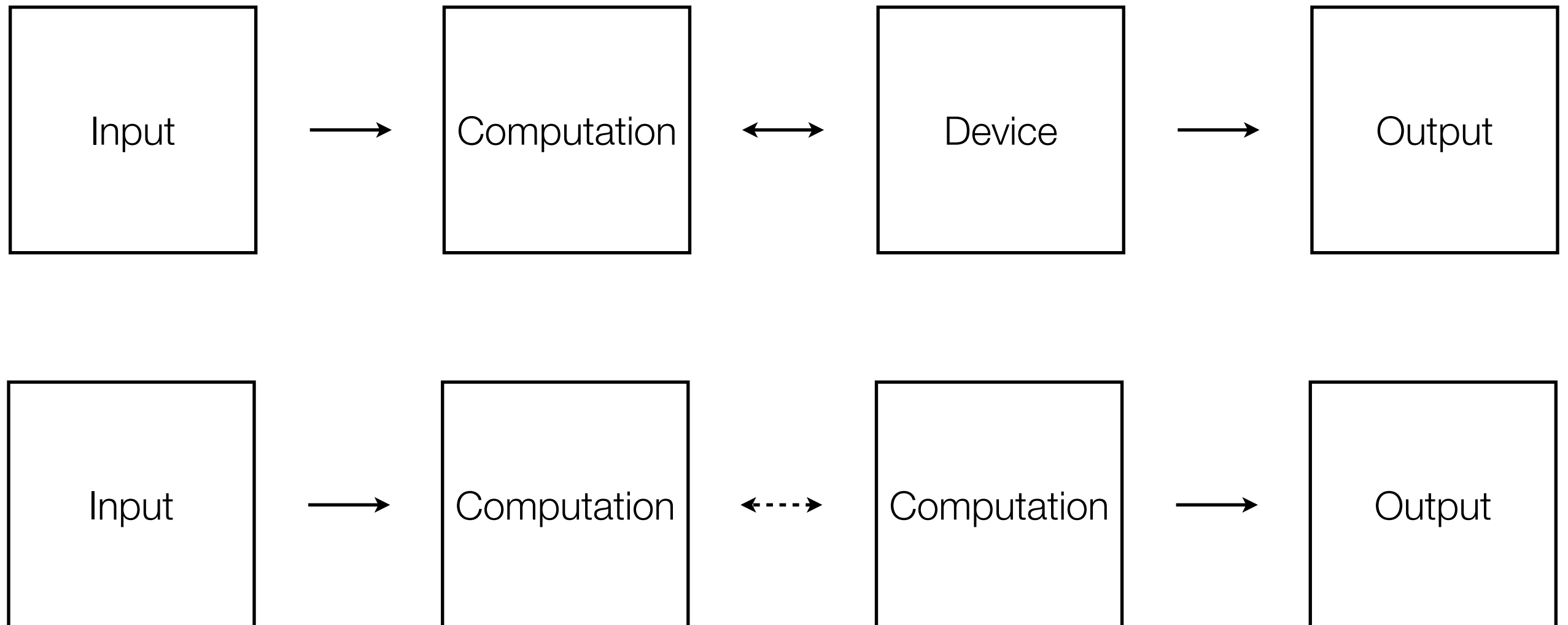


Images from *Control Freaks* by Haiyan Zhang, <http://failedrobot.com/thesis/>

Translation: Your Ideas to Electronics



Translation: Your Ideas to Electronics



Elements

Sensing

Actuation

Computation

Power

Connections

Communication

Storage

Sensing

Sensing

- interfaces
- light
- sound
- touch / contact
- motion
- proximity
- identity

Interfaces

Buttons



Switches



Knobs / Sliders

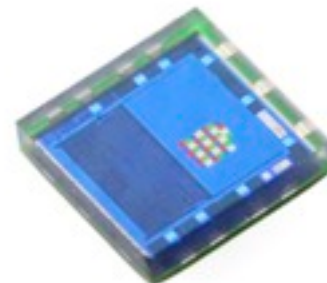


Light

Light-dependent resistor
(LDR) / photocell (\$1)



Color sensor (\$5-\$15)



Cameras (\$10 but hard to use)



Sound

Electret Microphone (\$1)



Speech Recognition Modules (\$50)



Contact

Pressure (FSR) \$6



Bend / Flex Sensor \$12



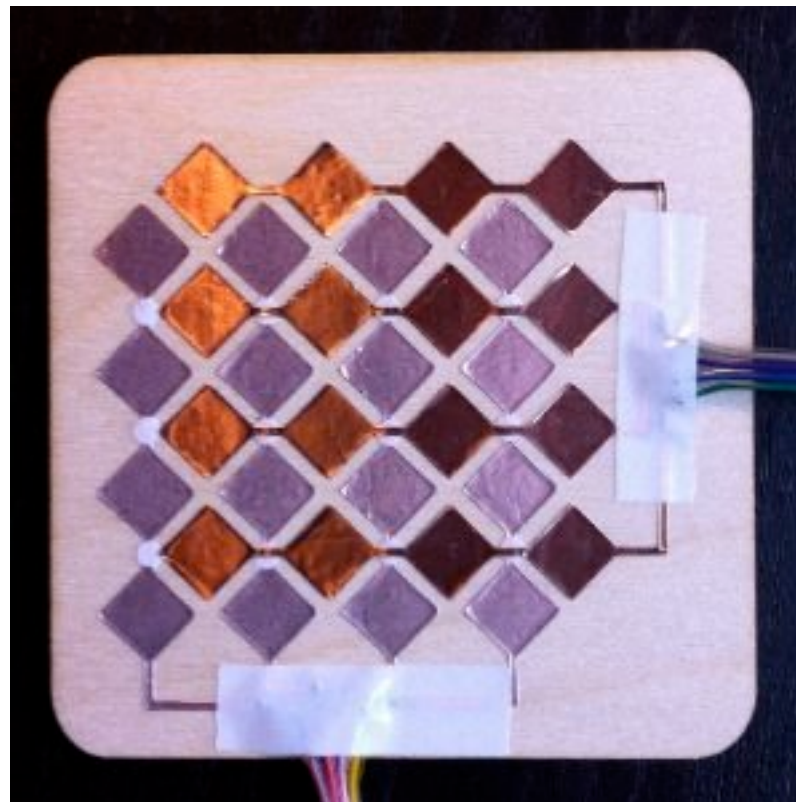
Soft Pot (\$18)



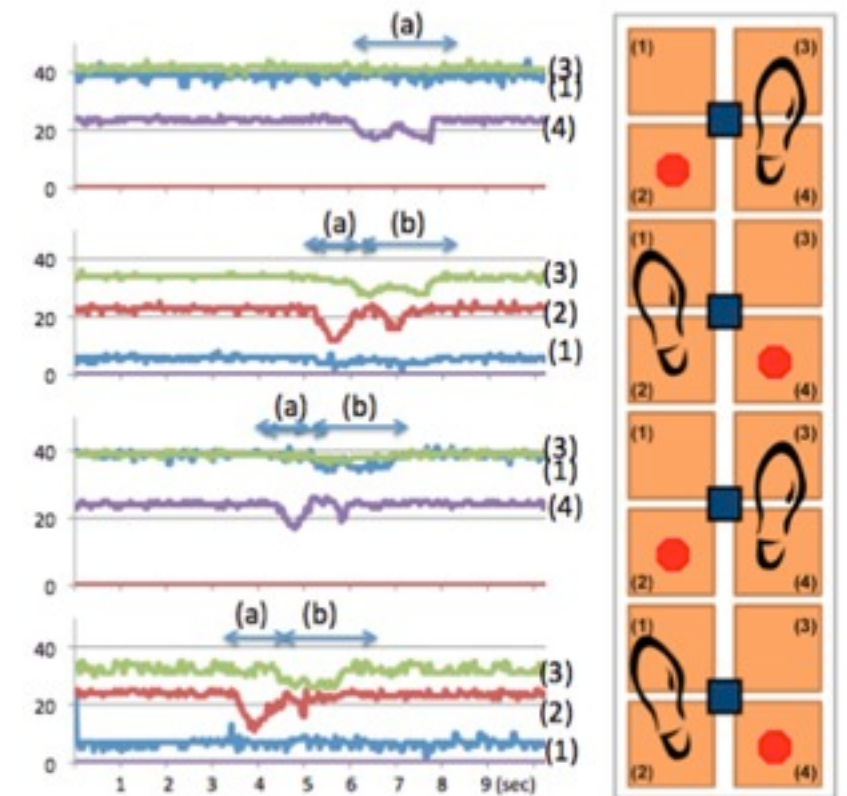
Capacitive Sensing



Tayo Falase



Matt Blackshaw



Nan-Wei Gong

Motion

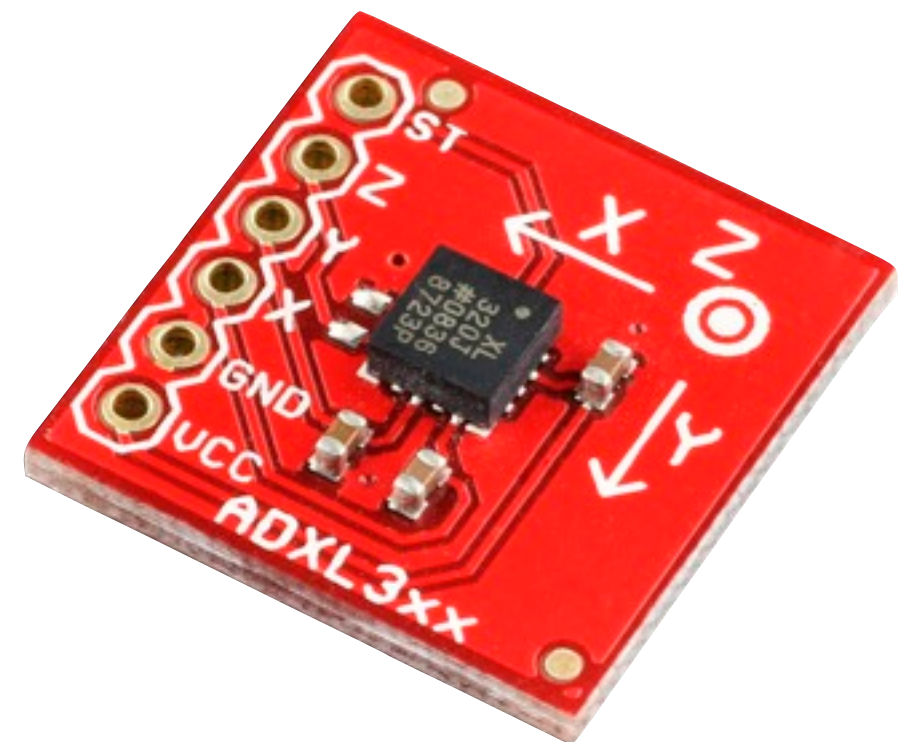
Tilt Sensor (\$2)



Piezo Sensor (\$3)



Accelerometer (\$30)



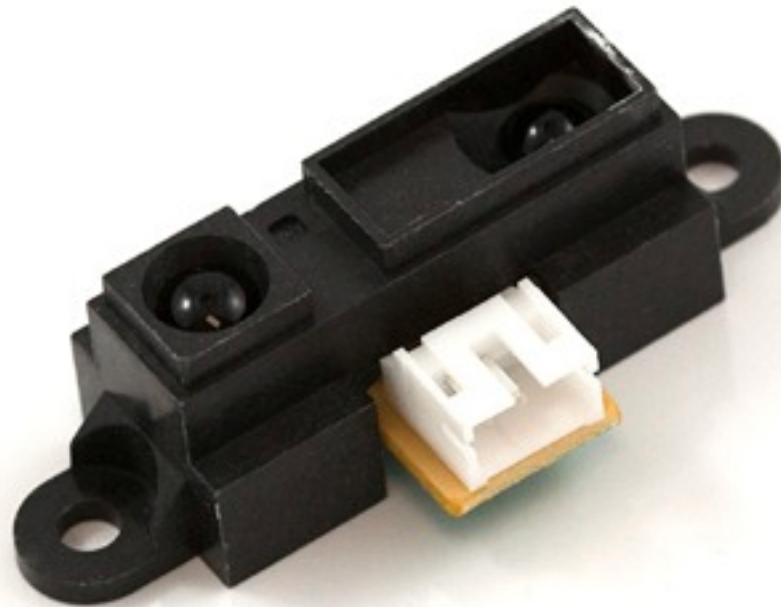
Distance and Proximity Sensors

Ultrasonic



Maxbotix LV-EZ1
\$25

Infrared



Sharp GP2Y0A21YK
\$14

PIR



PIR
\$10

Identity

RFID



Cards



Dealing w/ Noise

- Average N samples
- Running average (smoothing)
- Take lots of samples

Calibration

- Hard-coded range or threshold
- Take an average during power-up
- Look for changes

Interpretation

- Remember, you only get the data.
- *Acceleration* → *Gestures* is hard.
- Capacitive sensing can be flakey.

References

- Sensors (Joe Paradiso)
<http://resenv.media.mit.edu/classes/MAS836/>
- How to Make (almost) Anything (Neil Gershenfeld)
http://academy.cba.mit.edu/classes/input_devices/index.html
- SparkFun
<http://www.sparkfun.com/categories/23>
- Nan-Wei & Mark

Actuation

Actuation

- Light
- Motion
- Sound

LEDs (through-hole, 5mm, T 1-3/4)

Red, Green, Yellow
1.7V to 2.2V



White, Blue, and
“Super-Bright”
~3V



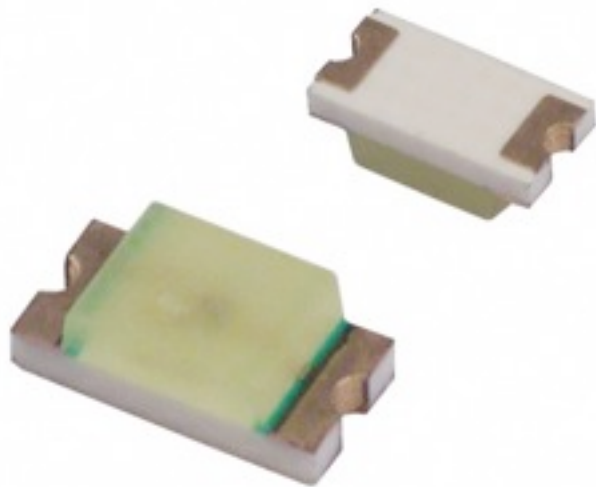
RGB
Colors differ in voltage



*Also come in infrared (IR) and ultraviolet (UV).
Also can get 3mm, 10mm.*

Other Form Factors

Surface Mount (1206)



“Piranha”
7.6 x 7.6mm



Luxeon Rebel (Philips)
Up to 1A.



Voltage, Resistance, Current (LED)

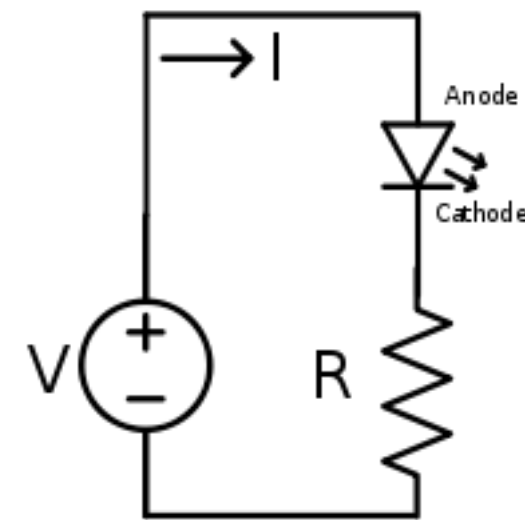
LED: 2V and 20 mA

Power Supply: 5V

What resistor do we need?

$5V - 2V = 3V$ (across resistor)

$3V / 20 \text{ mA} = 3V / 0.020A = 150\Omega$



Motors

DC (\$2)



Servo (\$5-\$25)
also continuous rotation



[video](#)

Stepper (\$5-\$50+)



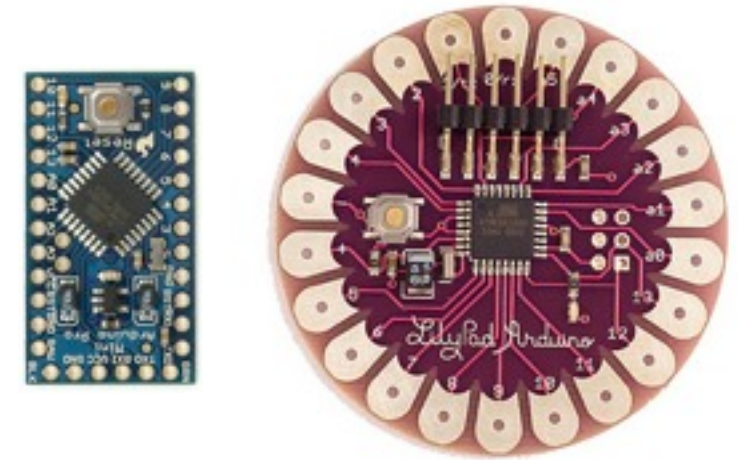
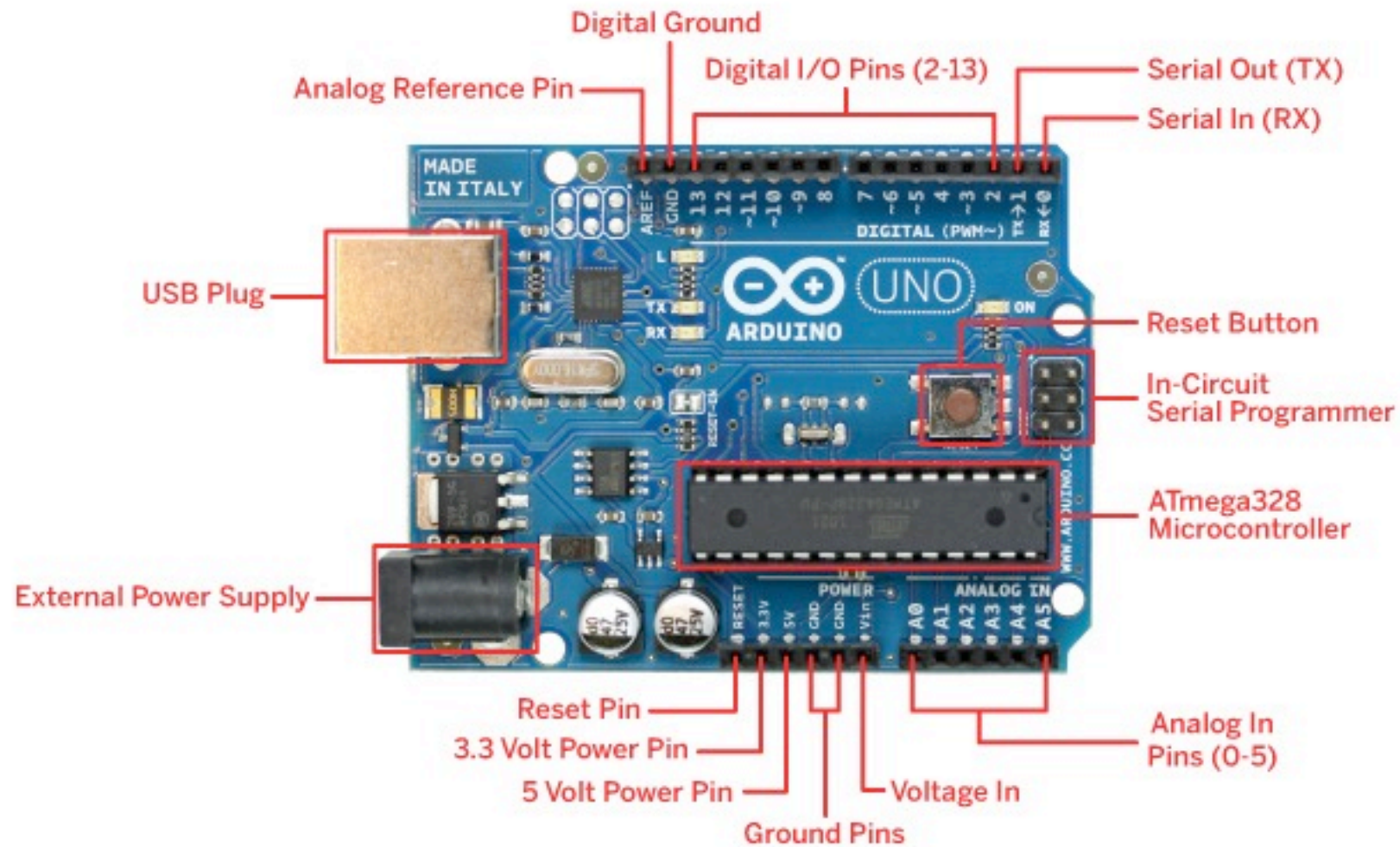
[video](#)

Dealing w/ High-Power

- Transistors (BJT)
- MOSFETs
- H-Bridges

Computation

Arduino



Source: Make Magazine

What can you do with an Arduino?

- 20 digital pins (input or output)
- 6 analog input pins
- 6 analog output (PWM) pins
- Various communication protocols

Analog-Digital Converter (ADC)

By default, 0V to 5V = 0 to 1023 (resolution of ~5 mV).

Also a 1.1V reference, that is 0V to 1.1V = 0 to 1023 (resolution of ~1mV).

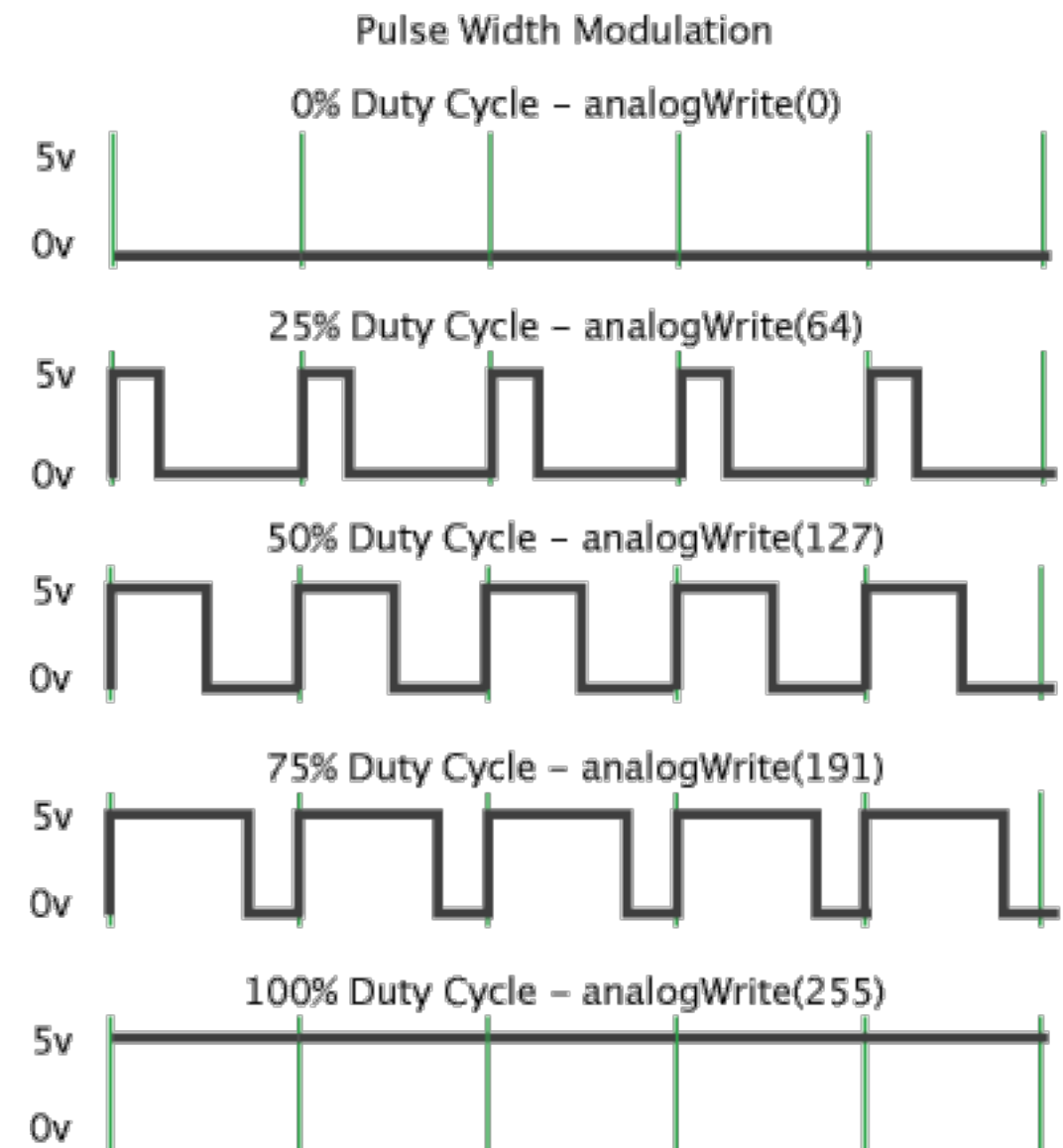
Also an external reference.

Analog input pins also work as digital pins.

Pulse-Width Modulation (PWM)

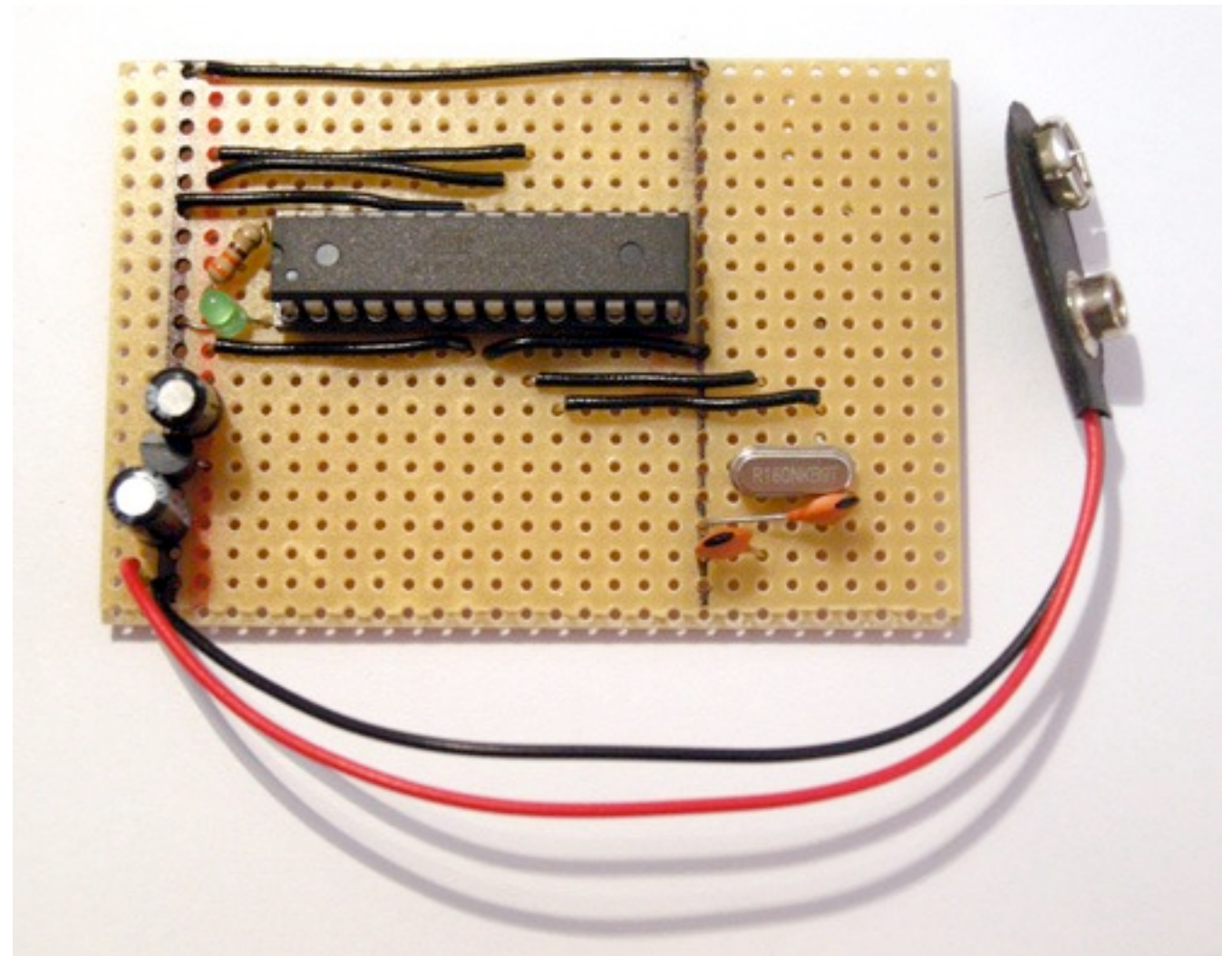
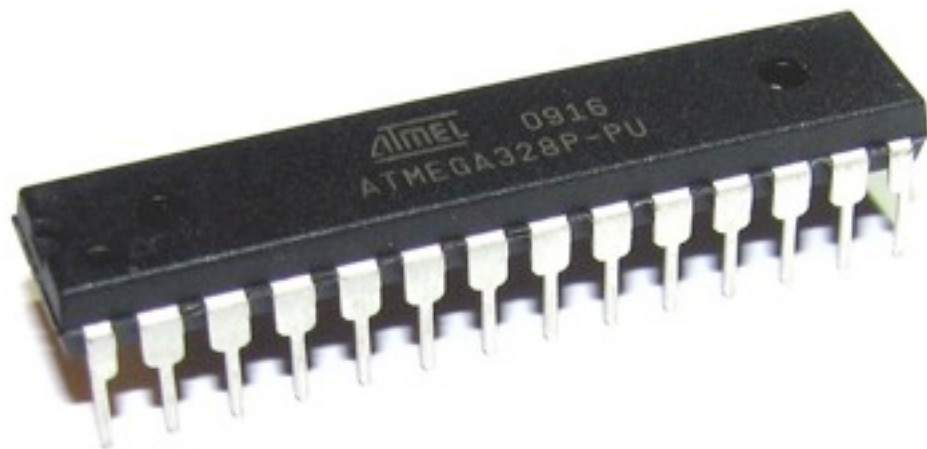
From 0 (always off) to 255 (always on).

Sometimes smoothed automatically.



ATmega328 (AVR)

- 16 MHz
- 32 KB flash
- 2 KB RAM



Other Microcontrollers

- ATtiny
- Other ATmega's
- PIC
- ARM
- Propeller

Other Development Boards

- Teensy
- Maple
- NETduino
- Microsoft Gadgeteer

Programming

- Assembly
- C
- Arduino

Resources

- Arduino website
<http://arduino.cc/>
- Make | Arduino
<http://blog.makezine.com/arduino/>
- LadyAda
<http://www.ladyada.net/learn/arduino/index.html>
- Google!

Power

Power

- Batteries
- Wall power (“mains”)
- USB power
- Other

Batteries

- AA, AAA (often 2, 3, or 4)
- 9V
- Coin Cell (e.g. the 3V CR2032, 20mm x 3.2mm)
- Rechargeable LiPo (3.7V)



Power Supplies

Wall Power Supplies
5V, 9V, 12V / 0.5-1A
\$5-\$10



Power Supplies
5V, 12V, 24V / 1-20A
\$25-\$50



Bench Power Supplies
Adjustable
\$200-\$500



Other Power Sources

Constant Current
LED Driver
e.g. MicroPuck
(350 mA from 3V)
or BuckToot
(350 mA from 5-28V)



USB Power
500 mA at 5V



ATX Power Supply
5V and 12V

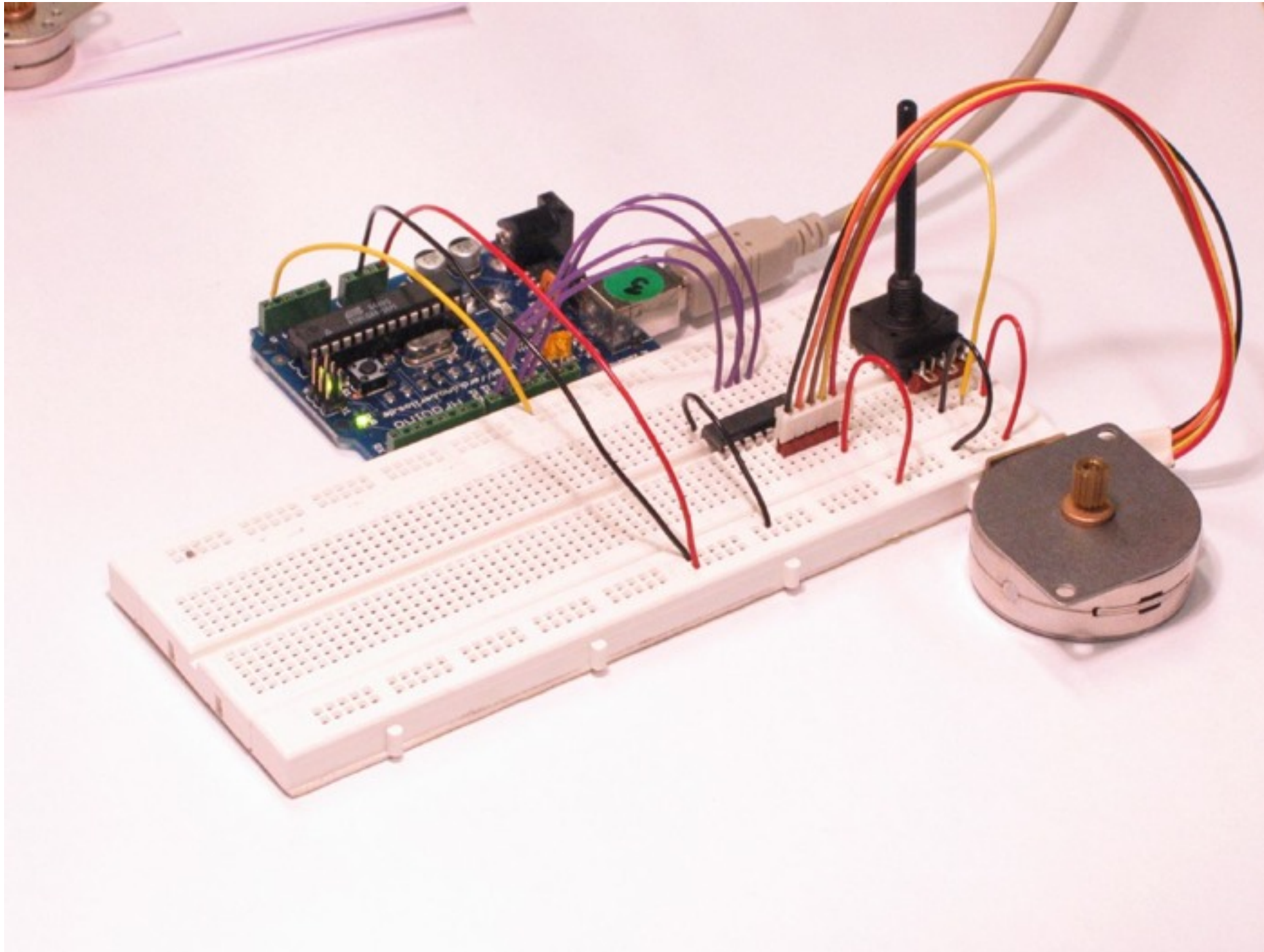


Other Power Sources

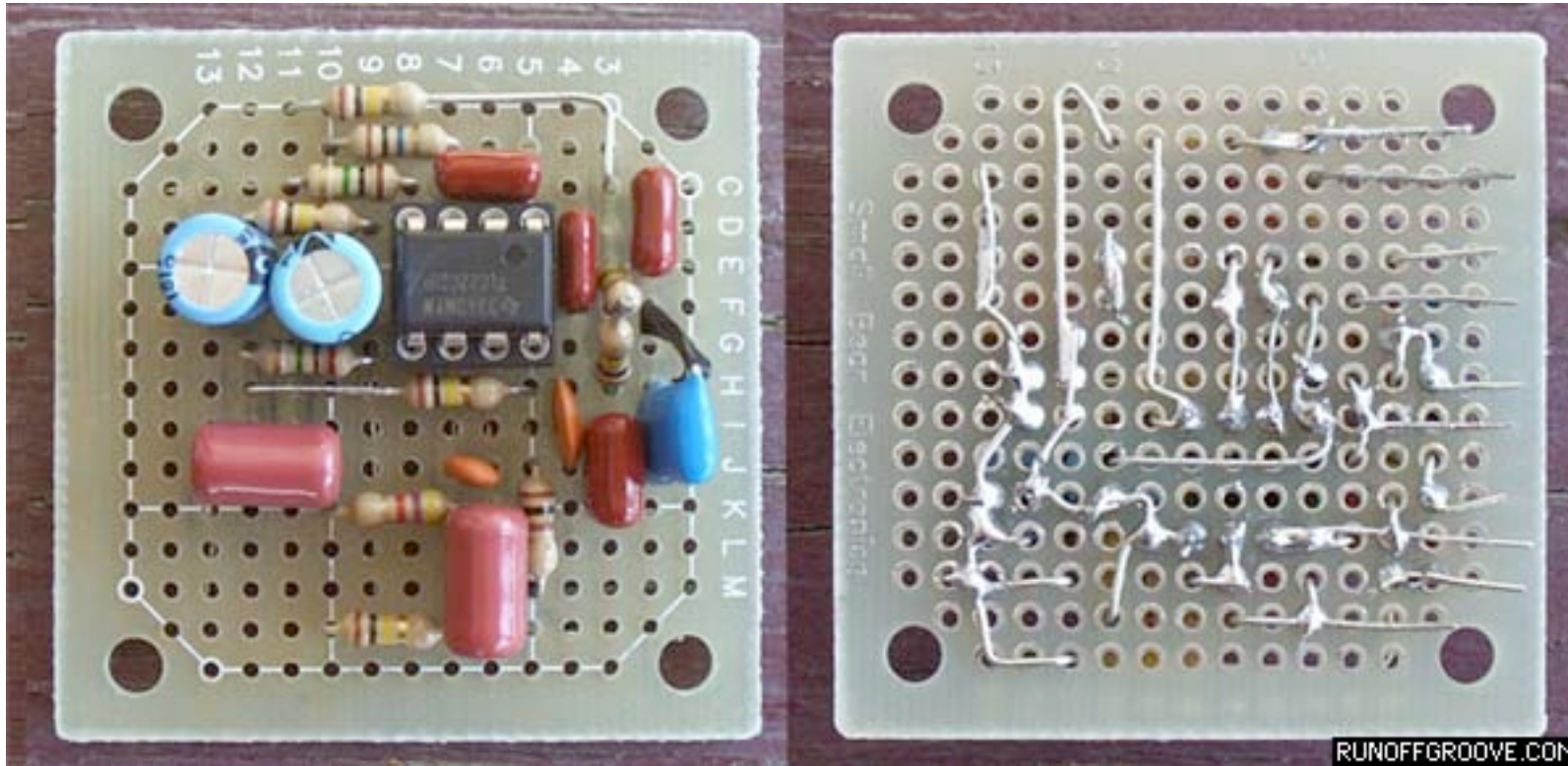
- Solar
- Piezo
- Generators
- Non-Electrical Activation (e.g. temperature, movement)

Connections

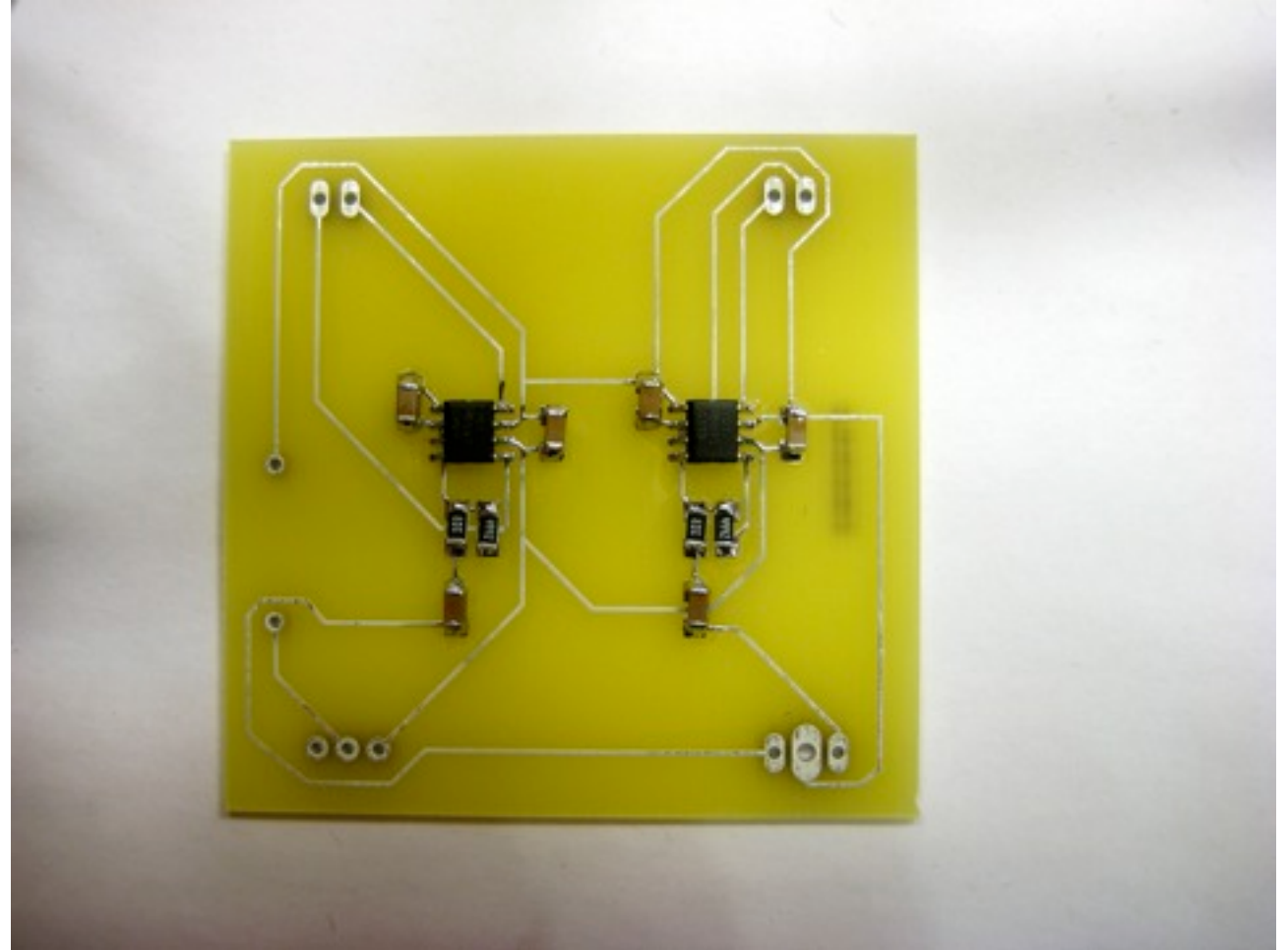
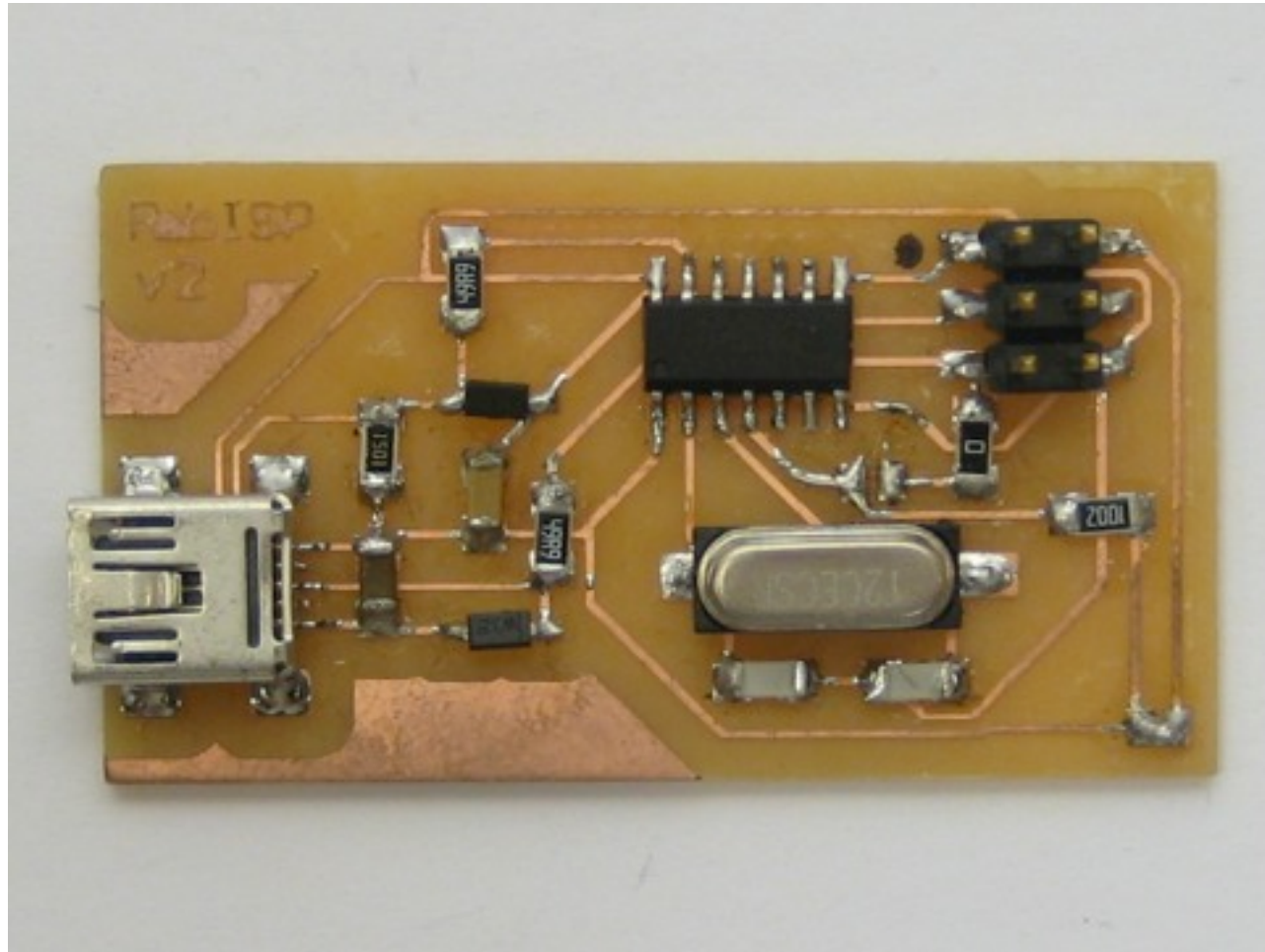
Breadboard



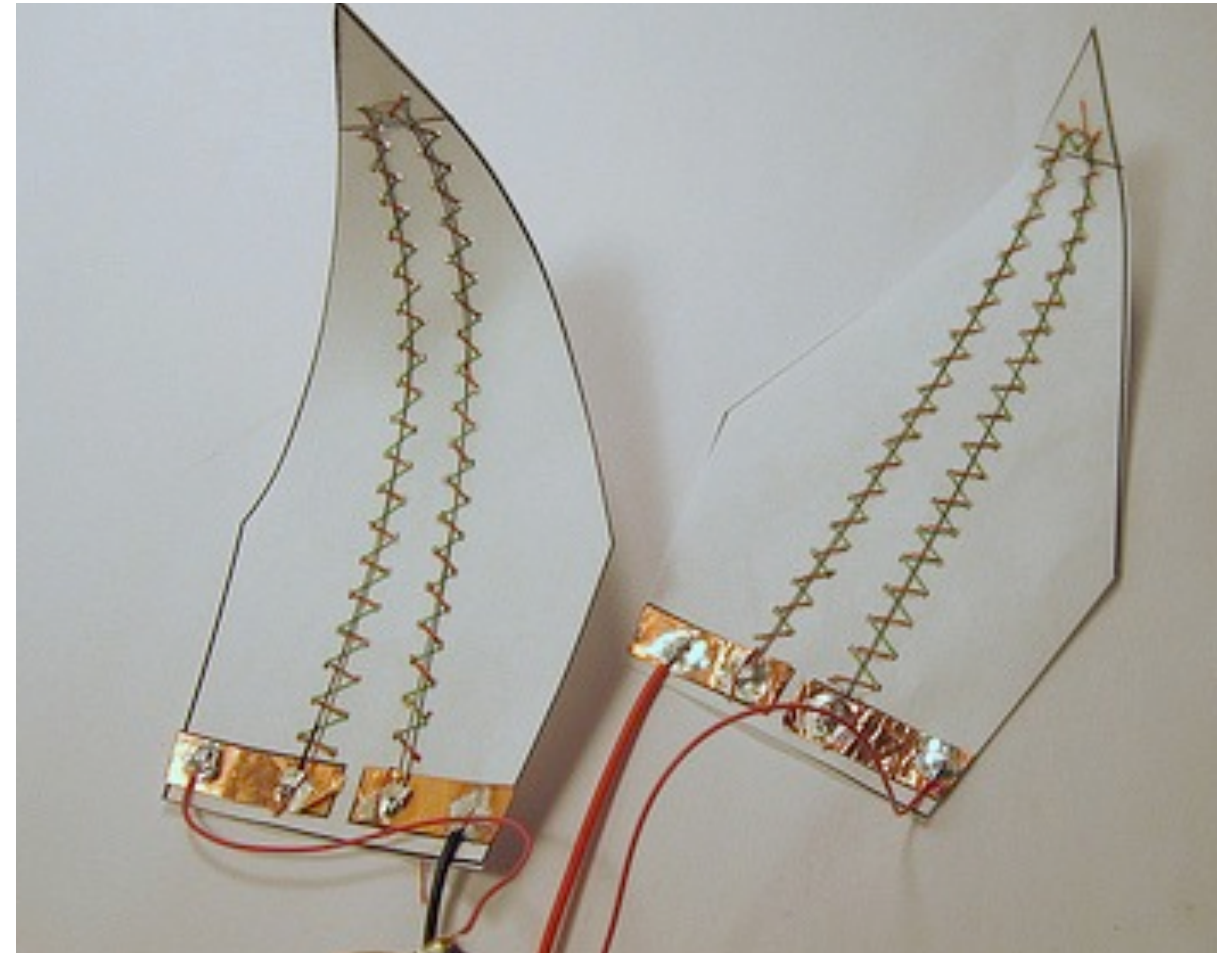
Perfboard / Protoboard / Stripboard / Millefori



Milling & Ordering



Soft Circuits



See: “How To Get What You Want” at <http://www.kobakant.at/DIY/>

Connectors

- Headers (female / male)
- Screw & spring terminals
- Phone / Ethernet: RJ9 (4p4c), RJ11 (6p6c, 6p4c, 6p2c), RJ45 (8p8c)
- Audio
- DC power jack (2.1 x 5.5 mm)

Communication

Wired

- Serial
- SPI
- I²C
- USB
- Ethernet

Wireless

- XBee
- Bluetooth
- WiFi
- IR

Resources

- *Making Things Talk*, Tom Igoe
- *Building Wireless Sensor Networks*, Rob Faludi

Storage

Storage

- On-chip flash (32KB), EEPROM (1KB)
- Flash chips (MBs)
- SD cards (GBs)

Resources

Suppliers

- SparkFun
- Digi-Key
- Mouser
- Jameco
- McMaster Carr

Parts Lists

- Fab Labs
<http://fab.cba.mit.edu/about/fab/inv.html>
- High-Low Tech
<http://hlt.media.mit.edu/?p=1300>
- Adafruit Parts Wiki
<http://www.ladyada.net/wiki/partselector>
- Octopart
<http://www.octopart.com/>

Resources

- *Physical Computing*, Dan O'Sullivan & Tom Igoe
- ITP Physical Computing
<http://itp.nyu.edu/physcomp/>
- Make Magazine
<http://makezine.com/>
- Bildr
<http://bildr.org/>

Advice

Keep building on a single prototype.

Don't take apart anything that works.

Making sense of sensor data is hard.

If it's flakey, add more capacitors.

Sometimes it's easier to fix everything that looks wrong (rather than actually finding the failure).

Keep it neat (e.g. use red wires for power, black wires for ground).

Sort by price!

Circuits

Basic Concepts

- Voltage (V), measured in volts (V)
- Resistance (R), measured in ohms (Ω)
- Current (I), measured in amperes (A)

kilo- = 1,000 ($k\Omega$, kV), mega- = 1,000,000 ($M\Omega$), milli = 1/1000 (mA, mV)

Ohm's Law

$$V = IR$$

Battery (Alkaline, 1.5V)



Resistor (10K Ω)

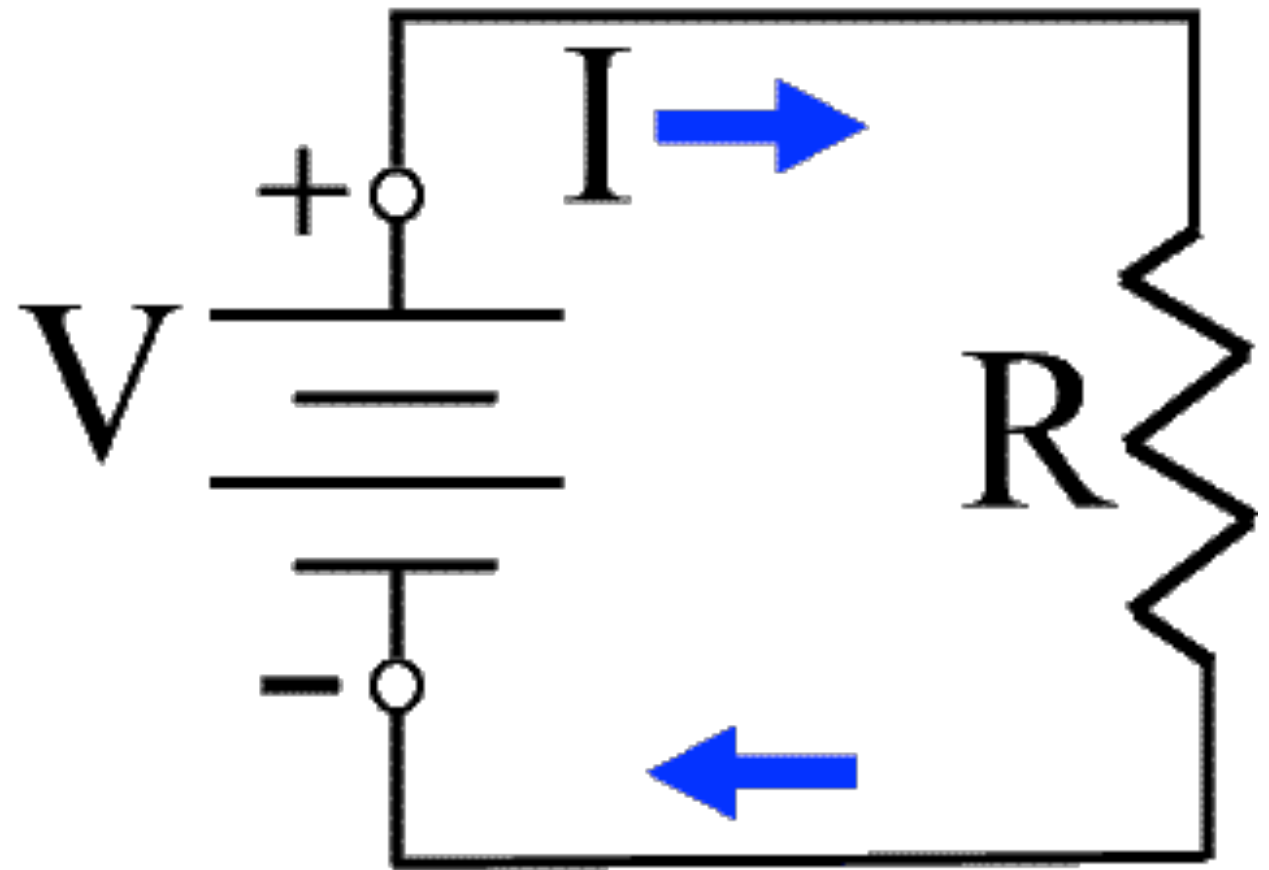


Circuit

$$V=IR$$

$$V/R=I$$

$$I = 1.5V / 10k\Omega = 0.15 \text{ mA}$$



Battery Charge

- Typically measured in milliamp hours (mAh)
- AAA: 1,200 mAh
- AA: 2,700 mAh
- C: 8,000 mAh
- D: 12,000 mAh
- 9V: 565 mAh

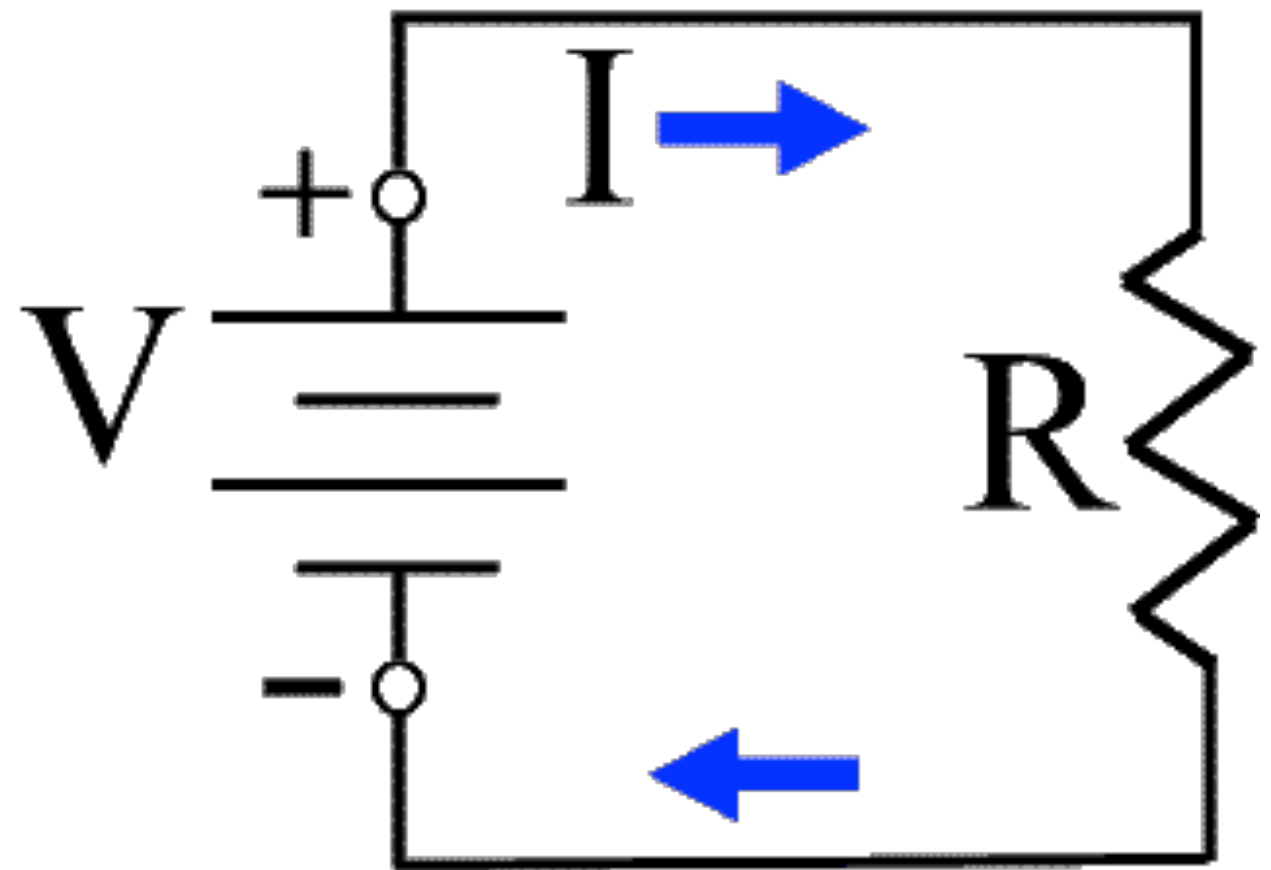


Circuit

$$I = 1.5V / 10k\Omega = 0.15 \text{ mA}$$

AAA: 1,200 mAh

$$1,200 \text{ mAh} / 0.15 \text{ mA} = 8000 \text{ h}$$



One more equation...

Power, measured in watts (W).

$$P=VI$$

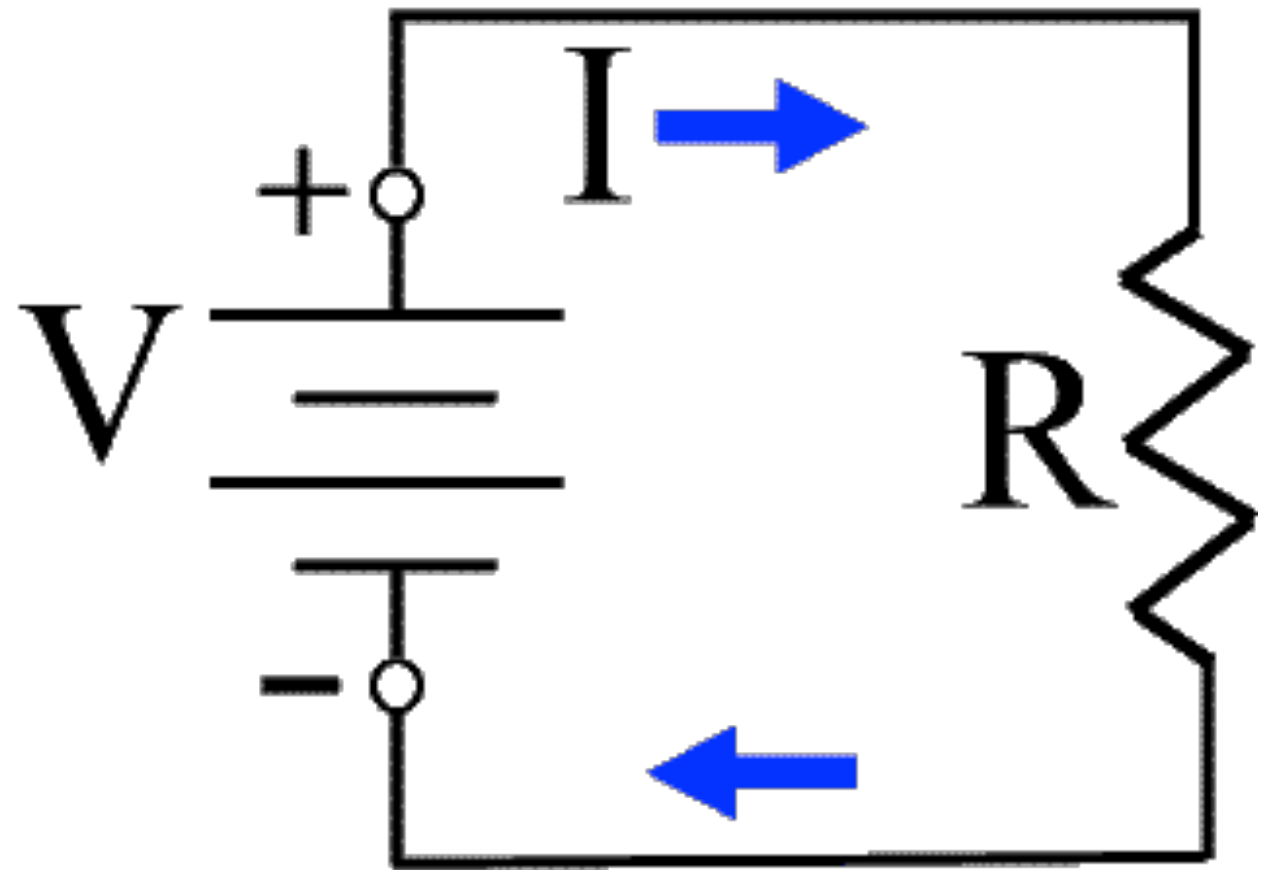
$$P=I^2R \text{ (remember, } V=IR\text{)}$$

Circuit

$$I = 1.5V / 10k\Omega = 0.15 \text{ mA}$$

$$P = VI$$

$$1.5V \times 0.15\text{mA} = 0.225 \text{ mW}$$



Resistor (1/4W)



Another Example

9V battery and 10Ω resistor

$$I = V / R = 9V / 10\Omega = 0.9 \text{ A}$$

$$P = IV = 0.9A \times 9V = 8.1W$$

Bad!

$$565 \text{ mAh} / 0.9A = \sim 0.62 \text{ hours} = \sim 38 \text{ minutes}$$

Series and Parallel
